

Go to market faster with NXP water pump solutions

# S12ZVM-EWP PMSM Water Pump Reference Design

The S12ZVM-EWP is a reference design board engineered for three-phase PMSM water pump applications with sensorless FOC dual shunt control, which provides high efficiency and dynamic performance.

# **OVERVIEW**

Based on the 16-bit S12 MagniV® S12ZVM mixed-signal microcontrollers, the S12ZVM-EWP board provides an A-sample of a PMSM electrical water pump ECU with hardware and software to accelerate the development and production of water pump products.

# **KEY FEATURES**

- ▶ Supports the MagniV S12ZVML64 MCU
- ▶ PMSM sensorless FOC algorithm supported
- ▶ 12 V system application, voltage supply range from 9 V to
- ▶ 7 A input current, up to 80 W input power
- ▶ Dual shunt current sampling
- ▶ Hardware overvoltage, undervoltage, overcurrent, and short protection
- ▶ PWM and LIN function integrated in 1 wire
- ▶ BDM and SCI integrated in 1 plug: 4 layers PCB with 1 layer components mounted
- ▶ Software over current, stall detection, under voltage, over voltage, over temperature protection
- ▶ Speed control by using PWM duty cycle and FreeMASTER
- ▶ Fault clear and restart auto-mode if related MACRO enabled

# **RUNTIME SOFTWARE**

- ▶ **\$12ZVM-EWP\_\$W:** Complete PMSM electrical water pump sensor-less FOC software package for \$12ZVM-EWP reference design
- ▶ AUTOMATH\_MCL: Automotive Math and Motor Control Library Set
- ▶ FreeMASTER Run-Time Debugging Tool
- ▶ MCATSW: Motor Control Application Tuning (MCAT) Tool
- ▶ CodeWarrior® for MCUs (Eclipse IDE)

# **TARGET APPLICATIONS**

▶ Electrical fuel, water and oil pumps



#### S12ZVML64 MCU AND S12ZVM-EWP BOARD SPECIFICATIONS

#### 128 KB 6-ch, 15-bit PWM 8 KB 12 V VREG 120 V / 70 mA, 170 mA with ballast Core S12Z ADC 2x16-ch, 12-bit 50 MHz PTU Speed 2 trigger input sources / 2 trigger output Package 64 LQFP GDU LIN-PHY Temp Up to +150°C 1 2 SCI, 1 SPI **EVDD** 1 ch. 5 V / 20 mA (source)

Part Number	Motor Type	Kit Contains
S12ZVM-EWP	PMSM	Board

#### **\$12ZVM-EWP BOARD**



#### MOTOR CONTROL ALGORITHM CONCEPT

