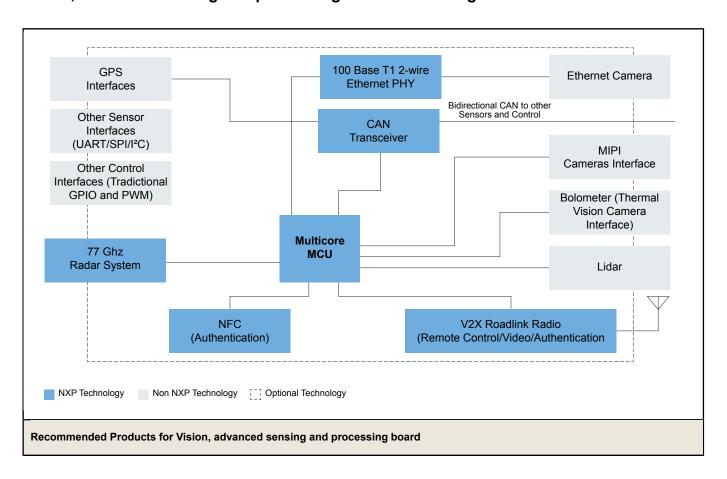


Vision, Advanced Sensing and Processing Board

Last Updated: Oct 6, 2022

Today's mobile robots (e.g., drones and rovers) need multiple sensor types to determine their location relative to their destination and potential obstacles: inertial sensors and sensor fusion algorithms to accurately know its position in space, or the movement and orientation of an actuator; pressure sensors to measure relative height above ground or as a measurement device for speed or turbulence; and magnetic sensors to provide high reliability angular or rotational measurement. NXP multicore 32 and 64-bit Arm® processors have the embedded hardware IP blocks for vision systems, as well as the processing power and interfaces needed.

Vision, advanced sensing and processing board Block Diagram



Multicore MCU	 i.MX7D: i.MX 7Dual Processors - Heterogeneous Processing with Dual Arm[®] Cortex[®]-A7 Cores and Cortex-M4 Core i.MX6D: i.MX 6Dual Processors - Dual-Core, 3D Graphics, HD Video, Multimedia, Arm[®] Cortex[®]-A9 Core i.MX 6 Processors: i.MX 6 Series Applications Processors: Multicore, Arm[®] Cortex[®]-A7 Core, Cortex-A9 Core, Cortex-M4 Core LS1012A: Layerscape[®] 1012A Low Power Processor S32V234: S32V2 Processors for Vision, Machine Learning and Sensor Fusion
Advanced Sensor systems	TEF810X: TEF810x Fully-Integrated 77 GHz Radar Transceiver MPL3115A2: Absolute Digital Pressure Sensor (20 to 110 kPa)
CAN Transceiver	TJA144x: Automotive CAN FD Transceiver Family TJA1463: CAN Signal Improvement Capability Transceiver with Sleep Mode
77 GHz Radar System	TEF810X: TEF810x Fully-Integrated 77 GHz Radar Transceiver S32R294: Radar Microcontroller
NFC	NTAG_I2C: NTAG I²C Plus 2K: NFC Forum Type 2 Tag with I²C Interface
Ethernet Interface	TJA1101: TJA1101B, IEEE 100BASE-T1 Compliant Automotive Ethernet PHY Transceiver
V2X	V2X Communications: V2X Communications

View our complete solution for Vision, Advanced Sensing and Processing Board.

Note: The information on this document is subject to change without notice.

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