

Safety power system basis chip with CAN FD and LIN transceivers

**11 November 2020** 

Product short data sheet

#### **General description** 1

The FS6500/FS4500 SMARTMOS devices are a multi-output, power supply, integrated circuit, including CAN Flexible Data (FD) and/or LIN transceivers, dedicated to the automotive market.

Multiple switching and linear voltage regulators, including low-power mode (32 µA) are available with various wake-up capabilities. An advanced power management scheme is implemented to maintain high efficiency over a wide range of input voltages (down to 2.7 V) and output current ranges (up to 2.2 A).

The FS6500/FS4500 includes configurable fail-safe/fail silent safety behavior and features, with two fail-safe outputs, becoming a full part of a safety oriented system partitioning, to reach a high integrity safety level (up to ASIL D).

The built-in CAN FD interface fulfills the ISO  $11898-2^{(13)}$  and  $-5^{(14)}$  standards. The LIN interface fulfills LIN protocol specifications 2.0,  $2.1^{(23)}$ ,  $2.2^{(24)}$ , and SAE J2602- $2^{(25)}$ .

High temperature capability up to  $T_A = 125$  °C and  $T_J = 150$  °C, compliant with AEC-Q100 Grade 1 automotive qualification.

#### Features and benefits 2

- Battery voltage sensing and MUX output pin
- Highly flexible SMPS pre-regulator, allowing two topologies: non-inverting buck-boost and standard buck
- Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)
- Linear voltage regulator dedicated to auxiliary functions, or to sensor supply (V<sub>CCA</sub> tracker or independent), 5.0 V, or 3.3 V
- Linear voltage regulator dedicated to MCU Analog/Digital (A/D) reference voltage or I/Os supply ( $V_{CCA}$ ), 5.0 V, or 3.3 V
- 3.3 V keep alive memory supply available in low-power mode
- Long duration timer, counting up to 6 months with 1.0 s resolution
- Multiple wake-up sources in low-power mode: CAN, LIN, IOs, LDT
- · Five configurable I/Os

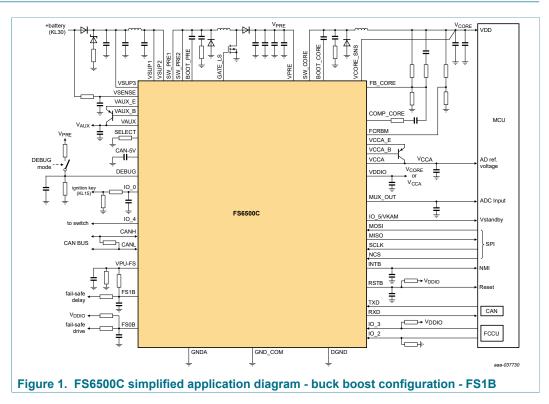
#### **Applications** 3

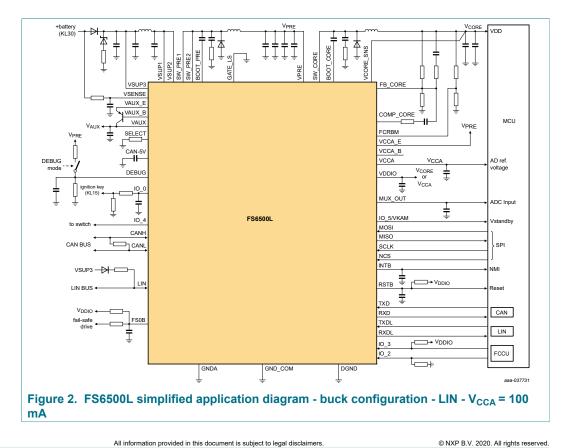
- Drive Train Electrification (BMS, Hybrid EV and HEV, Inverter, DC-DC, Alterno Starter)
- Drive Train Chassis and Safety (Active Suspension, Steering, Safety Domain Gateway)
- Power Train (EMS, TCU, Gear Box)
- ADAS (LDW, Radar, Sensor Fusion Safety area)



### Safety power system basis chip with CAN FD and LIN transceivers

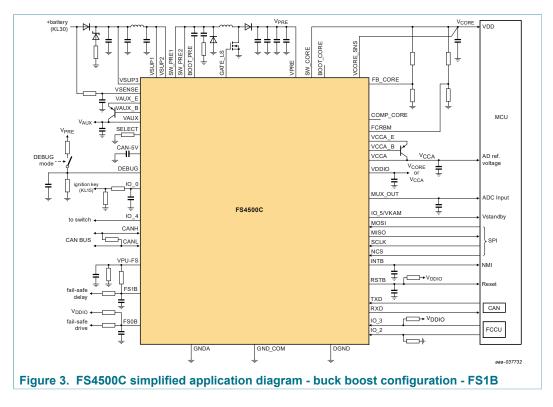
## 4 Simplified application diagrams





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## **5** Ordering information

### 5.1 Part number definition

## MC33FS <u>c</u> 5 <u>x</u> <u>y</u> <u>z</u> AE/R2

#### Table 1. Part number breakdown

Code	Option	Variable	Description		
С	4 series	V <sub>CORE</sub> type	Linear		
	6 series		DC-DC		
x	0	V <sub>CORE</sub> current	0.5 A or 0.8 A		
	1		1.5 A		
	2		2.2 A		
У	0	Functions	None		
	1		FS1B		
	2		LDT		
	3		FS1B, LDT		
	4		LDT, VKAM ON by default		

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## Safety power system basis chip with CAN FD and LIN transceivers

Code	Option	Variable	Description
z	Ν	Physical interface	None
	С		CAN FD
	L		CAN FD and LIN

### 5.2 Part numbers list

#### Table 2. Orderable part variations

Part Number	Temperature (T <sub>A</sub> )	Package	FS1B	LDT	VCORE	VCORE type	VKAM on	CAN FD	LIN	Note	
MC33FS4500CAE				0	0	0.5 A	Linear	by SPI	1	0	
MC33FS4500LAE			0	0	0.5 A	Linear	by SPI	1	1		
MC33FS4500NAE			0	0	0.5 A	Linear	by SPI	0	0	-	
MC33FS4501CAE			1	0	0.5 A	Linear	by SPI	1	0	-	
MC33FS4501NAE			1	0	0.5 A	Linear	by SPI	0	0		
MC33FS4502CAE			0	1	0.5 A	Linear	by SPI	1	0		
MC33FS4502LAE			0	1	0.5 A	Linear	by SPI	1	1		
MC33FS4502NAE			0	1	0.5 A	Linear	by SPI	0	0		
MC33FS4503CAE			1	1	0.5 A	Linear	by SPI	1	0		
MC33FS4503NAE			1	1	0.5 A	Linear	by SPI	0	0		
MC33FS6500CAE	1		0	0	0.8 A	DC-DC	by SPI	1	0	1	
MC33FS6500LAE			0	0	0.8 A	DC-DC	by SPI	1	1		
AC33FS6500NAE			0	0	0.8 A	DC-DC	by SPI	0	0		
AC33FS6501CAE	501CAE		1	0	0.8 A	DC-DC	by SPI	1	0		
AC33FS6501NAE	-	48-pin LQFP	1	0	0.8 A	DC-DC	by SPI	0	0		
AC33FS6502CAE	–40 °C		0	1	0.8 A	DC-DC	by SPI	1	0		
MC33FS6502LAE	to		0	1	0.8 A	DC-DC	by SPI	1	1	[1] [	
MC33FS6502NAE	125 °C	ovhooon ban	0	1	0.8 A	DC-DC	by SPI	0	0		
AC33FS6503CAE			1	1	0.8 A	DC-DC	by SPI	1	0		
MC33FS6503NAE			1	1	0.8 A	DC-DC	by SPI	0	0		
MC33FS6504LAE			0	1	0.8 A	DC-DC	by default	1	1		
MC33FS6510CAE			0	0	1.5 A	DC-DC	by SPI	1	0		
MC33FS6510LAE	-		0	0	1.5 A	DC-DC	by SPI	1	1		
MC33FS6510NAE	1		0	0	1.5 A	DC-DC	by SPI	0	0		
MC33FS6511CAE			1	0	1.5 A	DC-DC	by SPI	1	0	1	
MC33FS6511NAE			1	0	1.5 A	DC-DC	by SPI	0	0		
MC33FS6512CAE	1		0	1	1.5 A	DC-DC	by SPI	1	0	1	
MC33FS6512LAE			0	1	1.5 A	DC-DC	by SPI	1	1	1	
MC33FS6512NAE			0	1	1.5 A	DC-DC	by SPI	0	0		
MC33FS6513CAE			1	1	1.5 A	DC-DC	by SPI	1	0	1	
MC33FS6513NAE			1	1	1.5 A	DC-DC	by SPI	0	0		
MC33FS6514LAE			0	1	1.5 A	DC-DC	by default	1	1	1	
MC33FS6520CAE			0	0	2.2 A	DC-DC	by SPI	1	0		

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## Safety power system basis chip with CAN FD and LIN transceivers

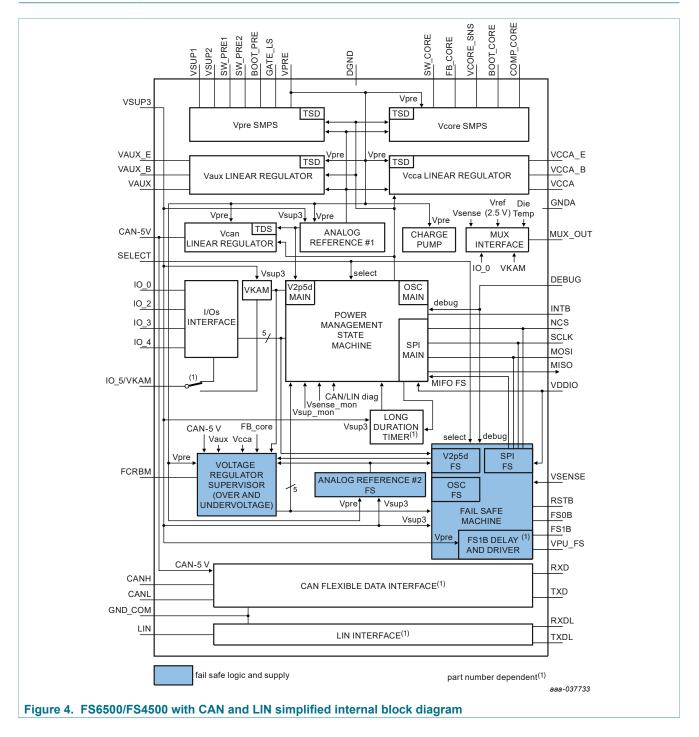
Part Number	Temperature (T <sub>A</sub> )	Package	FS1B	LDT	VCORE	VCORE type	VKAM on	CAN FD	LIN	Notes
MC33FS6520LAE			0	0	2.2 A	DC-DC	by SPI	1	1	
MC33FS6520NAE			0	0	2.2 A	DC-DC	by SPI	0	0	
MC33FS6521CAE	-		1	0	2.2 A	DC-DC	by SPI	1	0	
MC33FS6521NAE			1	0	2.2 A	DC-DC	by SPI	0	0	
MC33FS6522CAE	-		0	1	2.2 A	DC-DC	by SPI	1	0	
MC33FS6522LAE	-		0	1	2.2 A	DC-DC	by SPI	1	1	
MC33FS6522NAE			0	1	2.2 A	DC-DC	by SPI	0	0	
MC33FS6523CAE	1		1	1	2.2 A	DC-DC	by SPI	1	0	1
MC33FS6523NAE	1		1	1	2.2 A	DC-DC	by SPI	0	0	

[1] To order parts in tape and reel, add the R2 suffix to the part number.

[2] LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS1B is not, and vice versa. VKAM on by default is available on certain part numbers only.

#### Safety power system basis chip with CAN FD and LIN transceivers

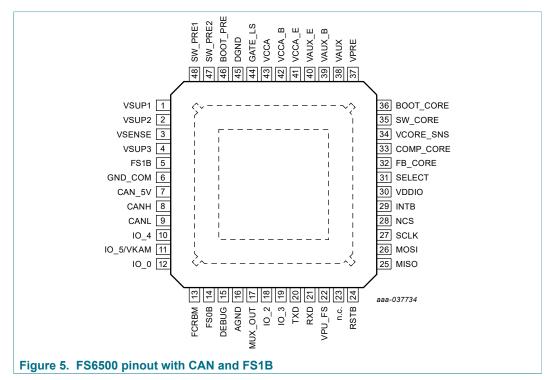
## 6 Block diagram

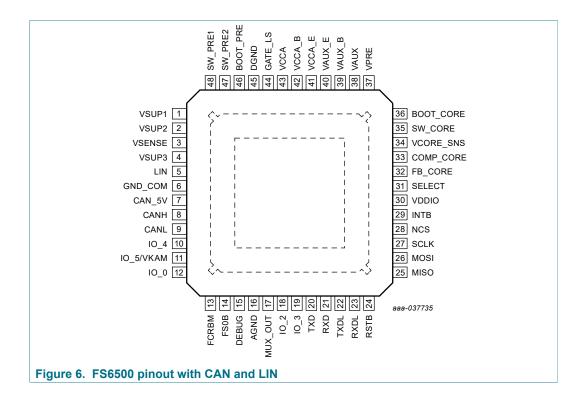


Safety power system basis chip with CAN FD and LIN transceivers

## 7 Pinning information

### 7.1 Pinning information

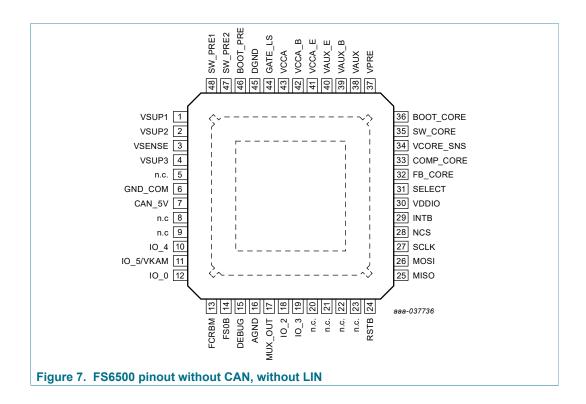


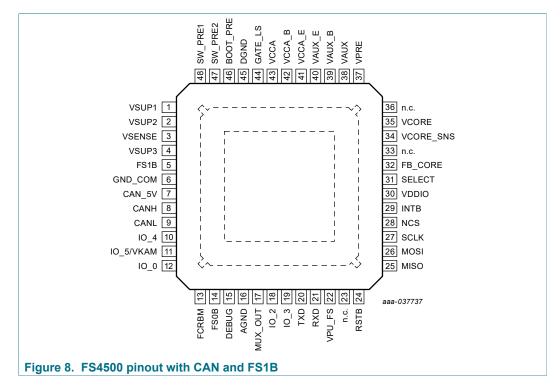


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## FS6500, FS4500

#### Safety power system basis chip with CAN FD and LIN transceivers





## Safety power system basis chip with CAN FD and LIN transceivers

## 7.2 Pin description

A functional description of each pin can be found in the full data sheet.

Pin number	Pin name	Туре	Definition		
1	VSUP1	A_IN	Power supply of the device. An external reverse battery protection diode in series is mandatory		
2	VSUP2	A_IN	Second power supply. Protected by the external reverse battery protection diode used for VSUP1. VSUP1 and VSUP2 must be connected together externally.		
3	VSENSE	A_IN	Sensing of the battery voltage. Must be connected prior to the reverse battery protection diode.		
4	VSUP3	A_IN	Third power supply dedicated to the device supply. Protected by the external reverse battery protection diode used for VSUP1. Must be connected between the reverse protection diode and the input PI filter.		
5	LIN	A_IN/OUT	LIN single-wire bus transmitter and receiver.		
	or FS1B	D_OUT	Second output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected, with a configurable delay or duration versus FS0B output terminal. Open drain structure.		
			exclusive. The differentiation is made by part numbers. When LIN is available, FS1B ther LIN, nor FS1B functions are used, this pin must be left open.		
6	GND_COM	GROUND	Dedicated ground for physical layers		
7	CAN_5V	A_OUT	Output voltage for the embedded CAN FD interface		
8	CANH	A_IN/OUT	CAN output high. If CAN function is not used, this pin must be left open.		
9	CANL	A_IN/OUT	CAN output low. If CAN function is not used, this pin must be left open.		
10	IO_4	D_IN A_OUT	Can be used as digital input (load dump proof) with wake-up capability or as an output gate driver <b>Digital input</b> : Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_5). <b>Wake-up capability:</b> Can be selectable to wake-up on edges or levels. <b>Output gate driver:</b> Can drive a logic level low-side NMOS transistor. Controlled by the SPI.		
11	IO_5/VKAM	A_IN D_IN A_OUT	Can be used as digital input with wake-up capability or as an analog output providing keep alive memory supply in low-power mode. <b>Analog input</b> : Pin status can be read through the MUX output terminal <b>Digital input</b> : Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_4). <b>Wake-up capability:</b> Can be selectable to wake-up on edges or levels. <b>Supply output:</b> Provide keep alive memory supply in low-power mode		
	VKAM can be enabled or disabled by default at power up. The differentiation is made by part numbers.				
12	IO_0	A_IN D_IN	Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) <b>Analog input</b> : Pin status can be read through the MUX output terminal <b>Digital input:</b> Pin status can be read through the SPI. <b>Wake-up capability:</b> Can be selectable to wake-up on edges or levels.		

### Table 3. FS6500/FS4500 pin definition

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Pin number	Pin name	Туре	Definition
13	FCRBM	A_IN	Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on $V_{CORE}$ (in parallel to the one used to set the $V_{CORE}$ voltage). If not used, this pin must be connected directly to FB_CORE.
14	FS0B	D_OUT	First output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected. Open drain structure.
15	DEBUG	D_IN	Debug mode entry input
16	AGND	GROUND	Analog ground connection
17	MUX_OUT	A_OUT	Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI.
18 19	IO_2:3	D_IN	Digital input pin with wake-up capability (logic level compatible) <b>Digital input</b> : Pin status can be read through the SPI. Can be used to monitor FCCU error signals from MCU for safety purposes.
			Wake-up capability: Can be selectable to wake-up on edges or levels.
20	TXD	D_IN	Transceiver input from the MCU which controls the state of the CAN-bus. Internal pull-up to VDDIO. If CAN function is not used, this pin must be left open.
21	RXD	D OUT	Receiver output which reports the state of the CAN-bus to the MCU
21		D_001	If CAN function is not used, this pin must be left open.
22	TXDL	D_IN	Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-up to VDDIO.
	or VPU_FS	A_OUT	Pull-up output for FS1B function.
	is not, and vi	ce versa.	e exclusive. The differentiation is made by part numbers. When LIN is available, FS1B
23	RXDL	D_OUT	Receiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.
24	RSTB	D_OUT	This output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to detect external reset and fault condition. Open drain structure.
25	MISO	D_OUT	SPI bus. Master input slave output
26	MOSI	D_IN	SPI bus. Master output slave input
27	SCLK	D_IN	SPI Bus. Serial clock
28	NCS	D_IN	Not chip select (active low)
29	INTB	D_OUT	This output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.
30	VDDIO	A_IN	Input voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.
31	SELECT	D_IN	Hardware selection pin for VAUX and VCCA output voltages
32	FB_CORE	A_IN	VCORE voltage feedback. Input of the error amplifier.
33	COMP_ CORE	A_OUT	Compensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).
34	VCORE_ SNS	A_IN	VCORE input voltage sense

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## Safety power system basis chip with CAN FD and LIN transceivers

Pin number	Pin name	Туре	Definition
35	SW_CORE	A_OUT	VCORE output switching point for FS6500 series
	or VCORE	A_OUT	VCORE output voltage for FS4500 series
36	BOOT_ CORE	A_IN/OUT	Bootstrap capacitor for VCORE internal NMOS gate drive For FS4500 series, this pin must be left open (NC).
37	VPRE	A_IN	VPRE input voltage sense
38	VAUX	A_OUT	VAUX output voltage. External PNP ballast transistor. Collector connection
39	VAUX_B	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Base connection
40	VAUX_E	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Emitter connection
41	VCCA_E	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Emitter connection
42	VCCA_B	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Base connection
43	VCCA	A_OUT	VCCA output voltage. External PNP ballast transistor. Collector connection
44	GATE_LS	A_OUT	Low-side MOSFET gate drive for non-inverting buck-boost configuration
45	DGND	GROUND	Digital ground connection
46	BOOT_PRE	A_IN/OUT	Bootstrap capacitor for the VPRE internal NMOS gate drive
47	SW_PRE2	A_OUT	Second pre-regulator output switching point
48	SW_PRE1	A_OUT	First pre-regulator output switching point

## 8 Maximum ratings

#### Table 4. Maximum ratings

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Symbol	Ratings	Value	Unit	Notes
Electrical rati	ngs	l	1	
V <sub>SUP1/2/3</sub>	DC voltage at power supply pins	-1.0 to 40	V	[1]
V <sub>SENSE</sub>	DC voltage at battery sense pin (with ext R in series mandatory)	-14 to 40	V	
V <sub>SW1,2</sub>	DC voltage at SW_PRE1 and SW_PRE2 Pins	-1.0 to 40	V	
V <sub>PRE</sub>	DC voltage at VPRE Pin	–0.3 to 8	V	
V <sub>GATE_LS</sub>	DC voltage at Gate_LS pin	–0.3 to 8	V	
V <sub>BOOT_PRE</sub>	DC voltage at BOOT_PRE pin	-1.0 to 50	V	
V <sub>SW_CORE</sub>	DC voltage at SW_CORE pin	–1.0 to 8	V	
V <sub>CORE_SNS</sub>	DC voltage at VCORE_SNS pin	0.0 to 8	V	
V <sub>BOOT_CORE</sub>	DC voltage at BOOT_CORE pin	0.0 to 15	V	
V <sub>FB_CORE</sub>	DC voltage at FB_CORE pin	–0.3 to 2.5	V	
V <sub>COMP_CORE</sub>	DC voltage at COMP_CORE pin	-0.3 to 2.5	V	
V <sub>FCRBM</sub>	DC voltage at FCRBM pin	–0.3 to 8	V	
V <sub>AUX_B,E</sub>	DC voltage at VAUX_B, VAUX_E pins	–0.3 to 40	V	
V <sub>AUX</sub>	DC voltage at VAUX pin	-2.0 to 40	V	
V <sub>CCA_B,E</sub>	DC voltage at VCCA_B, VCCA_E pins	–0.3 to 8	V	

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## Safety power system basis chip with CAN FD and LIN transceivers

Symbol	Ratings	Value	Unit	Notes
V <sub>CCA</sub>	DC voltage at VCCA pin	-0.3 to 8	V	
V <sub>DDIO</sub>	DC voltage at VDDIO pin	-0.3 to 8	V	
V <sub>CAN_5V</sub>	DC voltage on CAN_5V pin	-0.3 to 8	V	
V <sub>PU_FS</sub>	DC voltage at VPU_FS pin	-0.3 to 8	V	
V <sub>FSxB</sub>	DC voltage at FS0B, FS1B pins (with ext R in series mandatory)	-0.3 to 40	V	
V <sub>DEBUG</sub>	DC voltage at DEBUG pin	-0.3 to 40	V	
V <sub>IO_0,4</sub>	DC voltage at IO_0, IO_4 pins (with ext R in series mandatory)	-0.3 to 40	V	
V <sub>IO_5</sub>	DC voltage at IO_5 pin	-0.3 to 20	V	
V <sub>KAM</sub>	DC voltage at VKAM pin	-0.3 to 8	V	
V <sub>DIG</sub>	DC voltage at INTB, RSTB, MISO, MOSI, NCS, SCLK, MUX_OUT, RXD, TXD, RXDL, TXDL, IO_2, IO_3 pins	–0.3 to 8	V	
V <sub>SELECT</sub>	DC voltage at SELECT pin	-0.3 to 8	V	
$V_{BUS\_CAN}$	DC voltage on CANL, CANH pins	-27 to 40	V	
V <sub>BUS_LIN</sub>	DC voltage on LIN pin	-18 to 40	V	
I_lsense	V <sub>SENSE</sub> maximum current capability	-5.0 to 5.0	mA	
I_IO <sub>0, 4, 5</sub>	IOs maximum current capability (IO_0, IO_4, IO_5)	-5.0 to 5.0	mA	
ESD voltage				
Human body	r model (JESD22/A114) <sup>(20)</sup> – 100 pF, 1.5 kΩ			
V <sub>ESD-HBM1</sub>	All pins	±2.0	kV	[2]
V <sub>ESD-HBM2</sub>	<ul> <li>VSUP1, 2, 3, VSENSE, VAUX, IO_0,4, FS0B, FS1B, DEBUG</li> </ul>	±4.0	kV	
V <sub>ESD-HBM3</sub>	CANH, CANL	±6.0	kV	
V <sub>ESD-HBM4</sub>	• LIN	±8.0	kV	
Charge devic	ce model (JESD22/C101) <sup>(21)</sup> :			
V <sub>ESD-CDM1</sub>	All pins	±500	V	
V <sub>ESD-CDM2</sub>	Corner pins	±750	V	
System level	ESD (gun test)			
	<ul> <li>VSUP1, 2, 3, VSENSE, VAUX, IO_0, 4, 5, FS0B, FS1B</li> </ul>			
V <sub>ESD-GUN1</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2:(17)	±8.0	kV	
V <sub>ESD-GUN2</sub>	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±8.0	kV	
V <sub>ESD-GUN3</sub>	2.0 k $\Omega$ /150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±8.0	kV	
V <sub>ESD-GUN4</sub>	2.0 k $\Omega$ /330 pF powered according to ISO 10605 <sup>(16)</sup>	±8.0	kV	
	CANH, CANL			
V <sub>ESD-GUN5</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2:(17)	±15.0	kV	
V <sub>ESD-GUN6</sub>	330 $\Omega$ /150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±12.0	kV	
V <sub>ESD-GUN7</sub>	2.0 k $\Omega$ /150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±15.0	kV	
V <sub>ESD-GUN8</sub>	2.0 kΩ/330 pF powered according to ISO $10605^{(16)}$	±12.0	kV	
	• LIN			
V <sub>ESD-GUN9</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2: <sup>(17)</sup>	±12.0	kV	
V <sub>ESD-GUN10</sub>	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay conformance	±12.0	kV	

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Symbol	Ratings	Value	Unit	Notes
V <sub>ESD-GUN11</sub>	2.0 kΩ/150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±12.0	kV	
V <sub>ESD-GUN12</sub>	2.0 kΩ/330 pF powered according to ISO 10605 <sup>(16)</sup>	±12.0	kV	
Thermal ratin	igs			
T <sub>A</sub>	Ambient temperature	-40 to 125	°C	
TJ	Junction temperature	-40 to 150	°C	
T <sub>STG</sub>	Storage temperature	–55 to 150	°C	
Thermal resis	stance	l		
R <sub>0JA</sub>	Thermal resistance junction to ambient	30	°C/W	[3]
R <sub>ØJCTOP</sub>	Thermal resistance junction to case top	23.8	°C/W	[4]
R <sub>ØJCBOTTOM</sub>	Thermal resistance junction to case bottom	0.9	°C/W	[5]

All  $V_{\text{SUPS}}(V_{\text{SUP1/2/3}})$  must be connected to the same supply (Figure 1). Compared to AGND. [1]

[2] [3]

Per JEDEC JESD51- $6^{(18)}$  with the board (JESD51-7)<sup>(19)</sup> horizontal.

[4] Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC - 883 Method 1012.1)<sup>(22)</sup>.

[5] Thermal resistance between the die and the solder pad on the bottom of the packaged based on simulation without any interface resistance.

#### Packaging 9

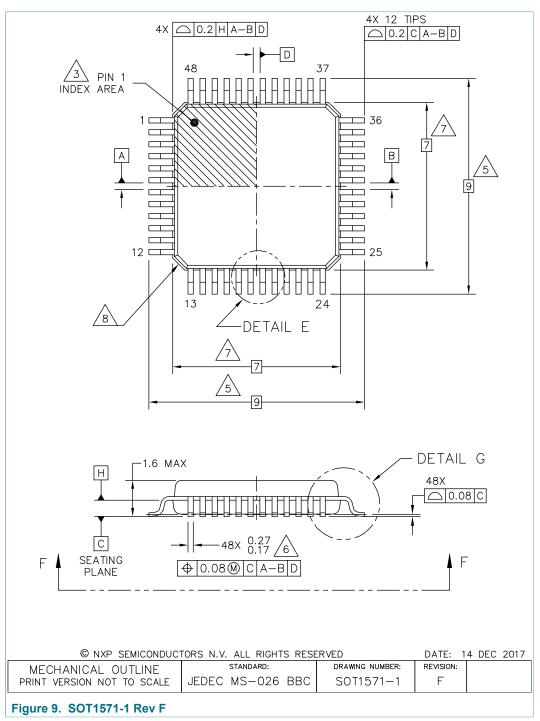
### 9.1 Package mechanical dimensions

Package dimensions are provided in package drawings. To find the most current package outline drawing, go to www.nxp.com and perform a keyword search for the drawing's document number.

#### Table 5. Package mechanical dimensions

Package	Suffix	Package outline drawing number
7.0 × 7.0, 48–Pin LQFP exposed pad, with 0.5 mm pitch, and a 4.5 × 4.5 exposed pad	AE	98ASA00173D

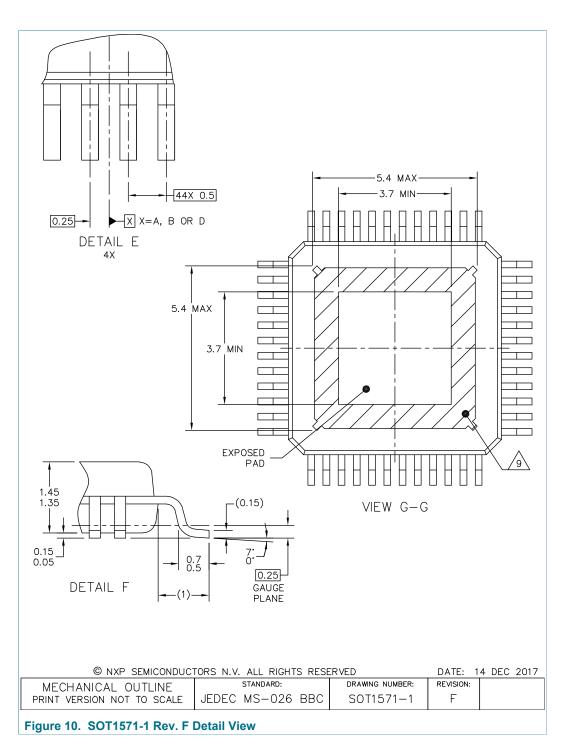
### Safety power system basis chip with CAN FD and LIN transceivers



## 9.2 Package outline

# FS6500, FS4500

Safety power system basis chip with CAN FD and LIN transceivers



#### Safety power system basis chip with CAN FD and LIN transceivers

NOTES:

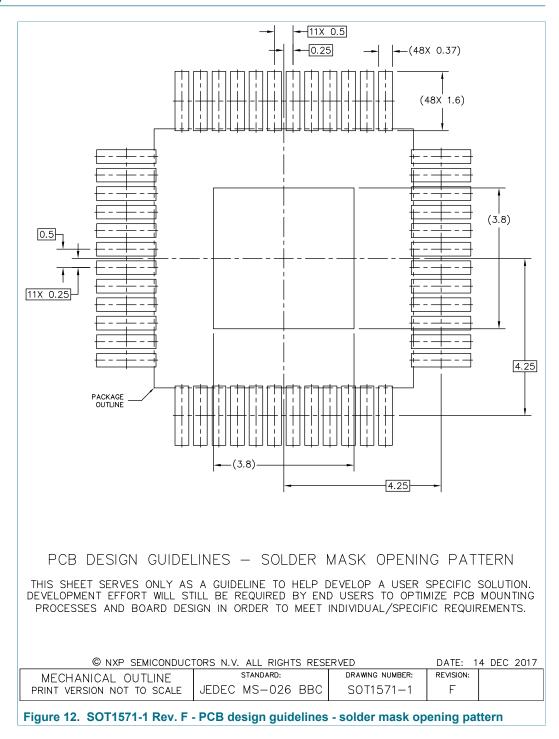
- 1. DIMENSIONS ARE IN MILLIMETERS.
- 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
- 3 PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY.
- 4. DATUMS A, B AND D TO BE DETERMINED AT DATUM PLANE H.
- 5. DIMENSION TO BE DETERMINED AT SEATING PLANE C.
- THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08MM AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07MM.
- A THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25MM PER SIDE. THIS DIMENSION IS MAXIMUM PLASTIC BODY SIZE DIMENSION INCLUDING MOLD MISMATCH.
- 8. EXACT SHAPE OF EACH CORNER IS OPTIONAL.
- A HATCHED AREA TO BE KEEP OUT ZONE FOR PCB ROUTING.

© NXP SEMICONDUCT	DATE: 1	4 DEC 2017		
MECHANICAL OUTLINE	STANDARD:	DRAWING NUMBER:	REVISION:	
	JEDEC MS-026 BBC	SOT1571-1	F	

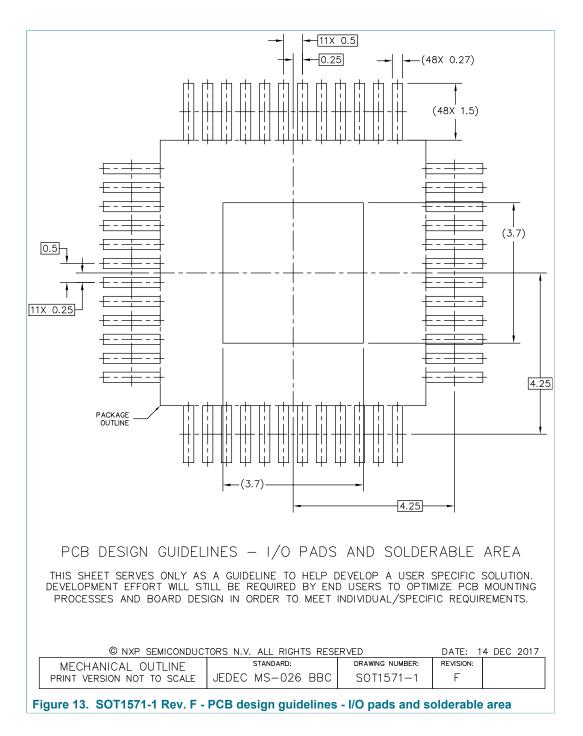
Figure 11. SOT1571-1 Rev F Notes

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## **10 Soldering**

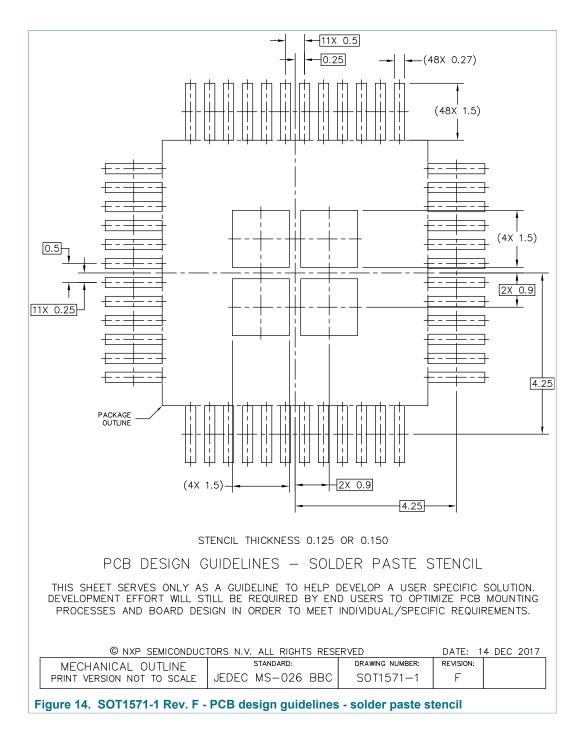


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### **11 References**

Obtain additional information on related NXP products and application solutions through the documents and URLs listed below.

- (1) AN5238 FS6500 and FS4500 Safe System Basis Chip Hardware Design and Product Guidelines Application Note <u>https://www.nxp.com/AN5238-DOWNLOAD</u>
- (2) AN4388 Quad Flat Package (QFP) https://www.nxp.com/files/analog/doc/app\_note/AN4388.pdf
- (3) **FS6500-FS4500PDTCALC** Power dissipation tool (Excel File) <u>https://www.nxp.com/files/analog/software\_tools/FS6500-FS4500-power-dissipation-calculator.xlsx</u>
- (4) **V**<sub>CORE</sub> compensation network simulation tool (CNC)<sup>[1]</sup>
- (5) **FMEDA** FS6500/FS4500 FMEDA<sup>[1]</sup>
- (6) **FS6500-FS4500SMUG** FS6500/FS4500 Safety manual user guide https://www.docstore.nxp.com/products/product-hierarchy?query=Sm5509
- (7) KITFS6522LAEEVM FS6522, System Basis Chip, DC-DC 2.2 A Vcore LDT, CAN, LIN <u>http://www.nxp.com/KITFS6522LAEEVM</u>
- (8) KITFS6523CAEEVM FS6523, System Basis Chip, DC-DC 2.2A Vcore FS1B LDT CAN <u>https://www.nxp.com/KITFS6523CAEEVM</u>
- (9) **KITFS4503CAEEVM** FS4503, System Basis Chip, Linear 0.5 A Vcore, FS1b, LDT, CAN https://www.nxp.com/KITFS4503CAEEVM
- (10) FS6500 product summary page https://www.nxp.com/FS6500
- (11) FS4500 product summary page https://www.nxp.com/FS4500
- (12) Analog power management homepage https://www.nxp.com/products/power-management
- (13) **ISO 11898-2:2003** Road vehicles Controller area network (CAN) Part 2: High-speed medium access unit <u>https://www.iso.org/standard/33423.html</u>
- (14) **ISO 11898-5:2007** Road vehicles Controller area network (CAN) Part 5: High-speed medium access unit with low-power mode

https://www.iso.org/contents/data/standard/04/12/41284.html

- (15) ISO 7637-2:2011 Road vehicles Electrical disturbances from conduction and coupling Part 2: Electrical transient conduction along supply lines only <u>https://www.iso.org/standard/50925.html</u>
- (16) **ISO 10605:2008** Road vehicles Test methods for electrical disturbances from electrostatic discharge <u>https://www.iso.org/standard/41937.html</u>
- (17) IEC 61000-4-2:2008 Electromagnetic compatibility (EMC) Part 4-2: Testing and measurement techniques -Electrostatic discharge immunity test https://webstore.iec.ch/publication/4189
- (18) **JESD51- 6** INTEGRATED CIRCUIT THERMAL TEST METHOD ENVIRONMENTAL CONDITIONS FORCED CONVECTION (MOVING AIR)
- (19) **JESD51-7** HIGH EFFECTIVE THERMAL CONDUCTIVITY TEST BOARD FOR LEADED SURFACE MOUNT PACKAGES
- (20) JESD22-A114F ELECTROSTATIC DISCHARGE (ESD) SENSITIVITY TESTING HUMAN BODY MODEL (HBM)

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- (21) **JESD22-C101F** FIELD-INDUCED CHARGED-DEVICE MODEL TEST METHOD FOR ELECTROSTATIC DISCHARGE WITHSTAND THRESHOLDS OF MICROELECTRONIC COMPONENTS
- (22) MIL-STD-883-1, Method 1012.1 TEST METHOD STANDARD MICROCIRCUITS
- (23) LIN Specification Package Revision 2.1:2006 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN-Spec\_Pac2\_1.pdf
- (24) LIN Specification Package Revision 2.2A:2010 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN\_2.2A.pdf
- (25) SAE J2602-2:201211 LIN Network for Vehicle Applications Conformance Test https://www.sae.org/standards/content/j2602/2\_201211/
- [1] Available upon request.

## **12 Revision history**

#### Table 6. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
FS6500-FS4500SDS v.7.0	20201111	Product data sheet	_	FS6500- FS4500SDS v.1.0	
Modifications	<ul> <li>The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors, N.V. Legal texts have been adapted to the new company name where appropriate.</li> <li>Updated short data sheet revision number from v.1.0 to v.7.0 to align with the revision number of the full data sheet.</li> <li>Changed product status from "Advance information" to "Product short data sheet".</li> <li>Global: Performed minor grammar, punctuation, and typographical changes throughout the document.</li> <li>Revised all images in Figures 1 through 7.</li> <li>Section 1, added new paragraph beginning with "High temperature capability"</li> <li>Section 2, removed the feature "36 V maximum input operating voltage".</li> <li>Section 9.2, updated the package outline images and created separate figures for each drawing in Figure 9, Figure 10, and Figure 11.</li> <li>Section 10, added new Soldering section and Figure 12, Figure 13, and Figure 14.</li> <li>Section 11, Updated reference to FS6500-FS4500SMUG - FS6500/FS4500 Safety Manual – user guide and added industry standard documents referenced in the narrative.</li> </ul>				
FS6500-FS4500SDS v.1.0	20171214	Data sheet: advance information			
Modifications	Initial release				

#### Safety power system basis chip with CAN FD and LIN transceivers

## **13 Legal information**

### 13.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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