

Programming the Keyboard Interrupt Module (KBI) on HC(S)08 MCUs

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Overview

This document is intended to serve as a quick reference for an embedded engineer to get the keyboard interrupt module up and running for any HC08 MCU. Basic knowledge about the functional description and configuration options will give the user a better understanding on how the KBI works. This application note provides examples which demonstrate one use of the KBI within the HC08 and HCS08 families of microcontrollers. The examples mentioned are intended to be modified to suit the specific needs for any application.

Keyboard Interrupt Module

The keyboard interrupt module (KBI) on HC08s can contain between 4 and 8 interrupt pins depending on the MCU (except for the HC08KH which has 20)—each with separate keyboard interrupt enable bits and one keyboard interrupt mask. These interrupts can be programmed to be either falling-edge-only, or falling-edge/low-level sensitive. The latest versions of the KBI contain rising edge also.

Hardware Example using the HC68HC908QY

The main Registers found within the KBI are:

1. The keyboard status and control register (KBISCR), which:
 - Flags a keyboard interrupt request (bit 3, KEYF)
 - Helps acknowledge keyboard interrupt requests (bit 2, ACKK)
 - Can prevent the output of the keyboard interrupt mask from generating interrupt requests (bit 1, IMASK)
 - Configures keyboard interrupt triggering sensitivity as falling-edge or falling-edge and low-level; this controls all pins (bit 0, MODEK)
2. The keyboard interrupt enable (KBIE), which:
 - Is capable of enabling and disabling each port pin to operate as a keyboard interrupt (KBIn)

Please refer to the [Appendix](#) for the different HC08s families and their capabilities in regards to the KBI.

Hardware Example using the HC68HC908QY

PTA2/KBI2 is configured as a KBI input. Enabling the KBI function on this pin also enables the internal pull-up resistor; this makes the default state for this KBI input a logic ‘1’. A push button is connected as shown in [Figure 1](#). When the button is pressed, the PTA2/KBI2 will read a logic ‘0’. PTA1 is configured as an output by setting the data direction register for PTA1, (DDRA1), and will turn on and off the LED with inverse logic. This means that the LED will turn on with a logic ‘0’ on PTA1, and it will turn off with a logic ‘1’ on the pin. For information on the calculations needed to find the value of R1, refer to application note AN1238: *HC05 MCU LED Drive Techniques Using the MC68HC705J1*.

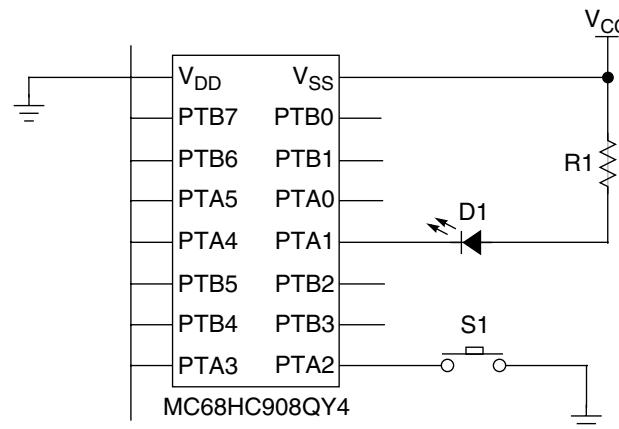


Figure 1. Hardware Example Connections

Code Example

This section contains the initialization code for the KBI using the MC68HC908QY4. Here, only pin 2 of the KBI (PTA2/KBI2) is initialized. During the initialization phase, interrupts are masked because it takes time for the internal pull up (typically 26 kΩ) to reach a logic ‘1’. Next, interrupts that may be pending are cleared, and then the keyboard interrupt is unmasked.

```
void KBI_init(void) {  
/*This procedure is to prevent False Interrupts at initialization */  
    KBSCR_IMASKK = 1;          /* Mask Keyboard interrupts */  
    KBIER_KBIE2 = 1;           /* Enables pin2 of KBI by setting KBIE2(PTA2) */  
    KBSCR_ACKK = 1;            /* Clear any false interrupts */  
    KBSCR_IMASKK = 0;          /* Unmask Keyboard interrupts */  
  
/* END Avoidance of False Interrupts */  
    /* Configures KBI Status & Control Register */  
    KBSCR = 0;                /* IMASKK=0: Clears KBI Mask Bit (Enable Ints)  
                                /* MODEK=0: Interrupt requests on Falling Edge Only */  
}
```

Using the routine shown above, the KBI is initialized and the program is ready for any keyboard interrupt. Whenever one occurs, the keyboard interrupt is serviced. The following interrupt service routine acknowledges the interrupt and then changes the logic state of PTA1 to blink the LED on and off.

```
interrupt 15 void _KB_Interrupt(void) {  
    KBSCR_ACKK = 1;           /* Acknowledge KB Interrupts */  
    PTA_PTA1 = ~PTA_PTA1;     /* Toggles the LED */  
}
```

Application Considerations

This example was developed using Metrowerks CodeWarrior IDE version 3.0 for HC(S)08, and was expressly made for the MC68HC908QY4 and for the MC68HC908GP32. Changes in the code may be required to initialize another MCU. It should also be taken into account that not all MCUs have an internal oscillator or an internal clock generator, so it may be necessary to connect and initialize a clock source. It should also be taken into consideration that a delay (20 ms typical) within the software is required to accommodate the mechanical stabilization time of the push button.

References

Refer to the following documents for more information on subjects in this application note.

- MC68HC908QY4 Technical Data Sheet
- AN1238: *HC05 MCU LED Drive Techniques Using the MC68HC705J1*

Appendix

This table provides information for the KBIs of several HC(S)08 MCUs.

	MCU	KBI	No. of KBI Pins	KBSCR Name	KBIER Name
M68HC(9)08 Family	HC(9)08AB	Yes	5	KBSCR	KBIER
	HC908AP	Yes	8	KBSCR	KBIER
	HC(9)08AS	No	—	—	—
	HC(9)08AZ	Yes	5	KBSCR	KBIER
	HC08BD	No	—	—	—
	HC908EY	Yes	5	KBSCR	KBIER
	HC908GP	Yes	8	INTKBSCR	INTKBIER
	HC908GR	Yes	4	INTKBSCR	INTKBIER
	HC908GT	Yes	8	INTKBSCR	INTKBIER
	HC908GZ	Yes	8	INTKBSCR	INTKBIER
	HC08JB	Yes	8	KBSCR	KBIER
	HC908JG	Yes	8	KBSCR	KBIER
	HC908JK	Yes	7	KBSCR	KBIER
	HC(9)08JL	Yes	7	KBSCR	KBIER
	HC08KH	Yes	20	KBxSCR	KBxIER
	HC908LD	Yes	8	KBSCR	KBIER
	HC908LJ	Yes	8	KBSCR	KBIER
	HC908LK	Yes	8	KBSCR	KBIER
	HC908MR	No	—	—	—
HCS08 Family	HC908QF	Yes	6	KBSCR	KBIER
	HC908QT	Yes	6	KBSCR	KBIER
	HC908QY	Yes	6	KBSCR	KBIER
	HC908RF	Yes	6	INTKBSCR	INTKBIER
	HC908RK	Yes	6	INTKBSCR	KBIER
	HC908SR	Yes	8	KBSCR	KBIER
HCS08 Family	HC9S08GB	Yes	8	KB1SCR	KB1PE
	HC9S08GT	Yes	8	KB1SCR	KB1PE
	HC9S08RC	Yes	12	KB#SCR	KBI#PE
	HC9S08RD	Yes	12	KB#SCR	KBI#PE
	HC9S08RE	Yes	12	KB#SCR	KBI#PE
	HC9S08RG	Yes	12	KB#SCR	KBI#PE

x = D,E, or F

= 1 or 2

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