

AN10403

Connecting ethernet interface with LPC2000

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Application note

Document information

Info	Content
Keywords	ARM, LPC2000, Ethernet, RTL8019
Abstract	This application note describes how to connect Ethernet interface with NXP LPC2000 series ARM MCU. Reference schematics and Ethernet driver source code is attached, with RTL8019AS as Ethernet controller. The document also shows how to configure uClinux Ethernet options in LPC22xx development system.

Revision history

Rev	Date	Description
01	20070207	Initial version.

Contact information

For additional information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

1. Introduction

1.1 About LPC2000

The 16/32-bit LPC2000 family is based on a 1.8 V ARM7TDMI-S core operating at up to 60 MHz together with a wide range of peripherals including multiple serial interfaces, 10-bit ADC and external bus options.

For more about LPC2000, refer to <http://www.nxp.com/>.

1.2 Ethernet

Ethernet is a local area network (LAN) technology that transmits information between computers by use of either coaxial or twisted pair cable. Ethernet uses a bus or star topology and supports data transfer rates of 10 Mbps, though newer systems use 100 Mbps.

The Ethernet specification serves as the basis for the IEEE 802.3 standard, which specifies the physical and lower software layers.

The RTL8019AS - 10 Mbit Ethernet controller by Realtek company - is a highly integrated Ethernet controller which offers a simple solution to implement a Plug and Play NE2000 compatible adapter with full-duplex and power down features.

You can find specification document and more products info on Realtek website.

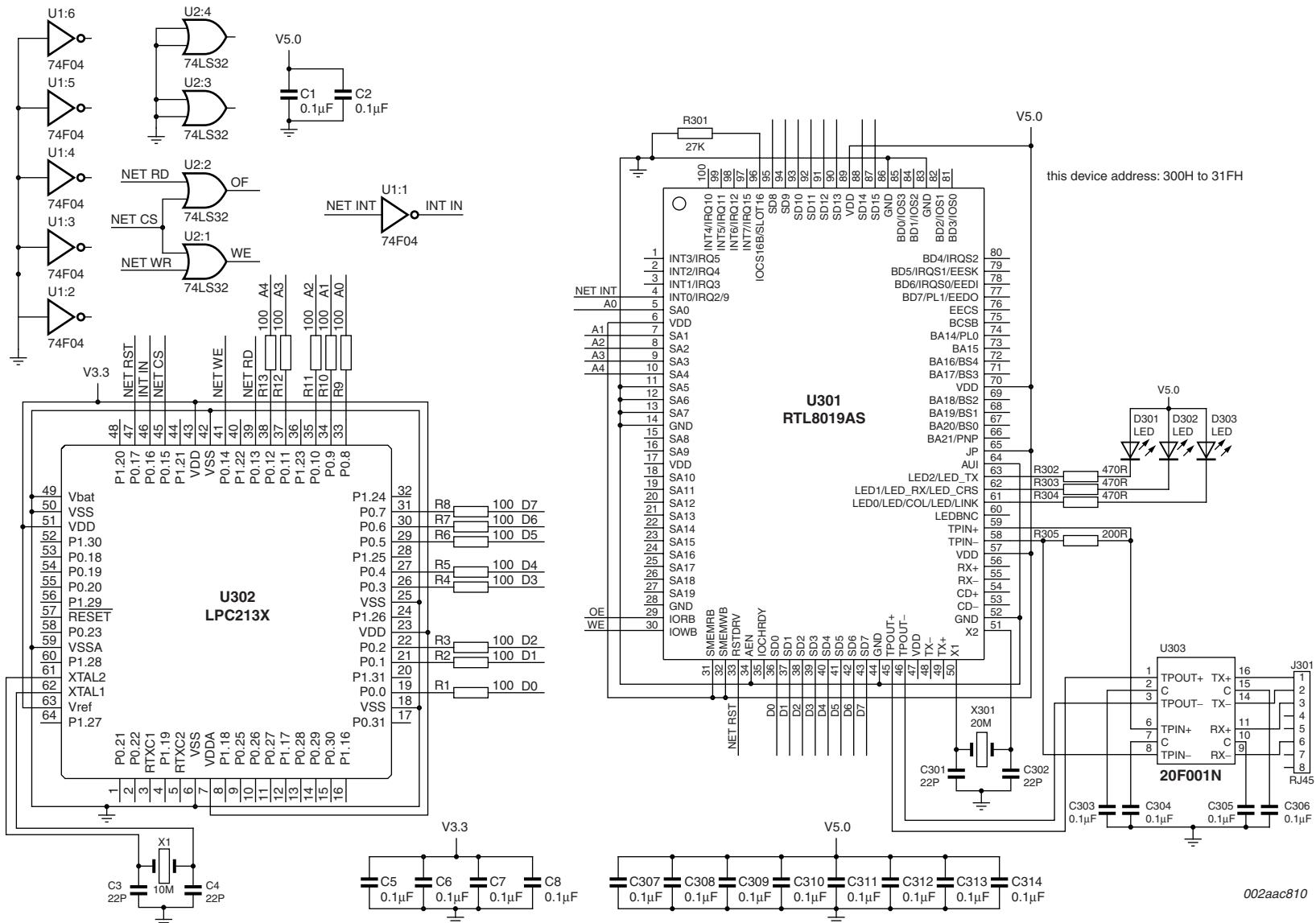
2. Connecting Ethernet with LPC2000

2.1 Connecting Ethernet with LPC21xx

The LPC21xx series, with tiny 64-pin package, are equipped with a variety of peripherals as UART, I2C, SPI, Timers, ADC/DAC, USB, etc, but without external bus interface. So GPIO is used to interface with RTL8019AS and 8-bit slots are selected in order to save GPIO.

The operation address of the RTL8019AS is 300H~31FH. [Fig 1](#) gives an example schematic connecting LPC21xx with RTL8019AS.

(Zoom in to see details.)



2.2 Connecting Ethernet with LPC22xx

With their 144-pin package, LPC22xx series have configurable external memory interface with up to four banks, each up to 16 MB and 8/16/32 bit data width.

[Fig 2](#) gives example schematics of connecting LPC22xx with RTL8019AS.

(Zoom in to see details.)

The address map of RTL8019AS in the system is as:

```
1     CS0:      For external flash memory.
      2 0x80000000 - 0x807FFFFF      8 MB
      3 0x80400000 - 0x80FFFFFF      reserve
      4
5     CS1:      For external SRAM
      6 0x81000000 - 0x811FFFFF      2 MB
      7 0x81200000 - 0x81FFFFFF      reserve
      8
9     CS2:      For Ethernet
      10 0X82000000 - 0X821FFFFF      2 MB
      11 0X82200000 - 0X822FFFFFF      reserve
      12
13    CS3:      For others
      14 0x83000000 - 0x8303FFFF      LCD
      15 0x83040000 - 0x8307FFFF      USB
      16 0x83080000 - 0x830BFFFF      IDE
      17 0x83100000 - 0x831BFFFF      CF Card
      18 0x8320 0000 to 0x83FF FFFF      reserve
```

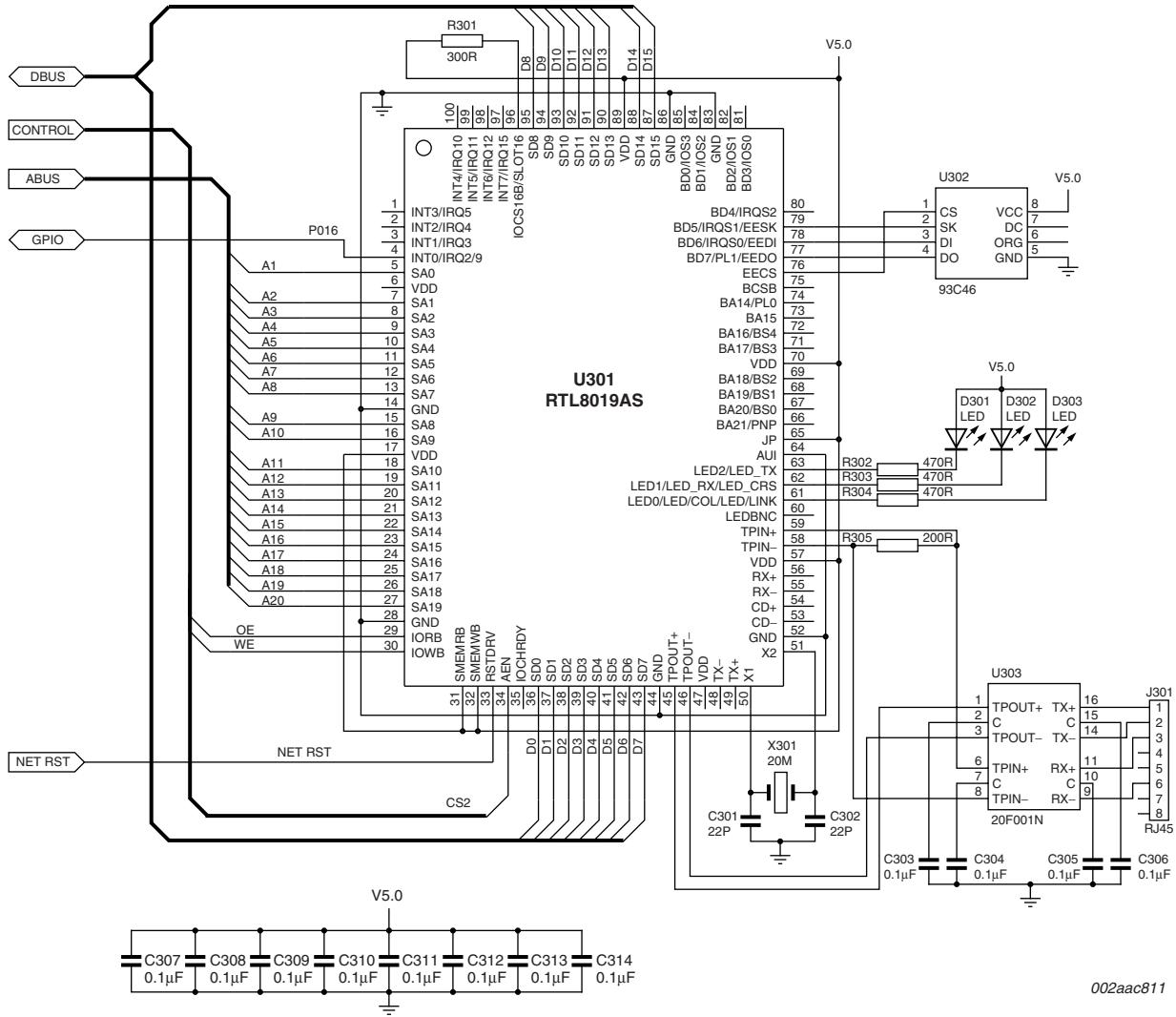


Fig 2. LPC22xx + RTL8019AS

3. Ethernet in uClinux system

Linux operating system has superior network function support, including full TPC/IP, PPP stack, etc. Its branch uClinux – Linux without MMU support – retains this advantage.

This section lists how to configure Ethernet options in uClinux system when connecting Ethernet controller with LPC22xx. To know about uClinux for LPC22xx, please read related application note “AN_Getting Started uClinux with LPC22xx”.

In the uClinux-dist directory on your Linux PC, type below command:

```
19 [root@mylinux uClinux-dist]# make menuconfig
```

At the first Main Menu, set vendor/product selection as below:

```
20 Vendor/Product Selection --->
21     (Philips) Vendor
22     (LPC22xx) Philips Product
```

Set “Kernel/Library/Defaults Selection” as below.

```
23 Kernel/Library/Defaults Selection --->
24 (linux-2.6.x) Kernel Version
25 (uClibc) Libc Version
26 [ ] Default all settings
27 [*] Customize Kernel Settings
28 [*] Customize Vendor/User Settings
29 [ ] Update Default Vendor Settings
```

Please toggle at least the two menus about kernel and user settings.

In the first popup window about ‘Linux Kernel Configuration’, enter the ‘Networking support’. Set and toggle the options as below. Especially TCP/IP networking and Network device options are definitely needed.

```
30 Networking support --->
31     [*] Networking support
32         Networking options --->
33             [*] Packet socket
34             ...
35             [*] Unix domain sockets
36             ...
37             [*] TCP/IP networking
38     [ ] Amateur Radio support --->
39     [ ] IrDA(infrared) subsystem support --->
40     [ ] Bluetooth subsystem support --->
41     [*] Network device support
42         .....
43         Ethernet (10 or 100Mbit) --->
44             [ ] Ethernet (10 or 100Mbit)
45             [*] NE2000/NE1000 support
46             [*] RT8019AS support
```

For the Ethernet options in network device support, user can use ‘NE2000/NE1000 support’ provided by original uClinux system.

Or user can create his own RTL8019AS option and toggle it. The difference is to use different device driver programs. See related description in next section.

In the second popup window for user settings, enter the Network Applications and toggle any application program you need. These application programs are provided in the official uClinux distribution package. In case the application is toggled and compiled into the Linux file system, it can be used as a Linux command in the console such as “ping, arp, ifconfig, etc.”

E.g.

```
47 Network Applications --->
48      [*] arp
49      [*] httpd
50      [*] ifconfig
51      [*] ping
52      [*] telnet
```

If selecting “httpd”, we can also create a web server on the board and display some web pages in the web browser on PC.

E.g.

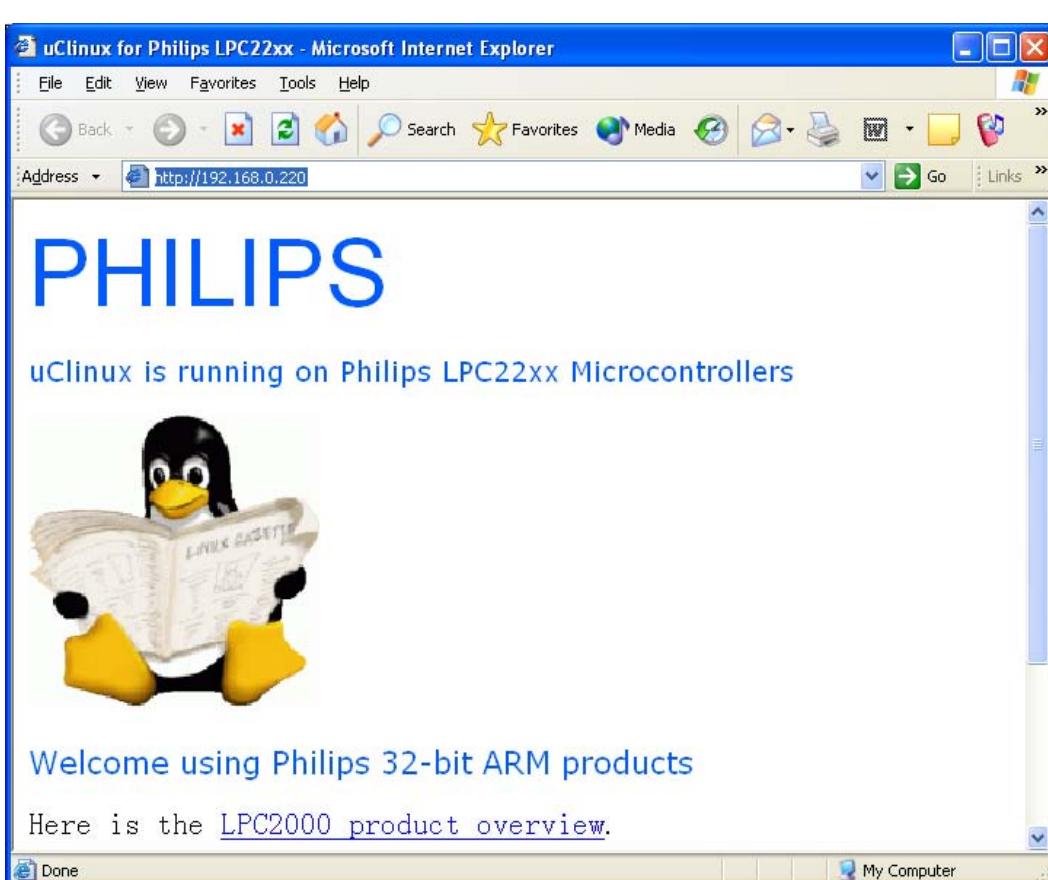


Fig 3. Web browser example

4. Ethernet driver

To drive an Ethernet controller, an Ethernet driver program should run on the microcontroller. The appendix gives an example source code based on [Fig 2](#) connecting scheme.

Please note that this reference source code is only a draft hint but not perfect. It provides the basic driver flow such as init, transmit, receive, interrupt, etc.

In the uClinux system, we can find the NE2000 compatible Ethernet driver at
./linux-2.6.x/drivers/net/ne.c, 8390.c, 8390.h.

Since RTL8019AS is NE2000 compatible, these codes can be used as the RTL8019AS driver after adding some necessary initialization and definitions extra for RTL8019AS.

Or user can develop his own Ethernet device driver under uClinux.

Appendix A Reference RTL8019AS Driver Program

```
53  /*****
54   rtl8019.h
55   This software may be used and distributed according to the terms
56   of the GNU General Public License, incorporated herein by reference.
57  *****/
58 #define SHIFT(x) (x<<1)
59
60 #define BaseAddr  (0x82000000+SHIFT(0x300))
61 #define RWPORT      (BaseAddr+SHIFT(0x10))    /* dma read write address,
form 0x10 - 0x17 */
62 #define RstAddr     (BaseAddr+SHIFT(0x18))    /* reset register, 0x18,
0x1a, 0x1c, 0x1e even address is recommanded */
63
64 /* page 0 */
65 #define Pstart      (BaseAddr+SHIFT(1))    /* page start */
66 #define Pstop       (BaseAddr+SHIFT(2))    /* page stop */
67 #define BNRY        (BaseAddr+SHIFT(3))
68 #define TPSR        (BaseAddr+SHIFT(4))    /* transmit page start */
69 #define TBCR0       (BaseAddr+SHIFT(5))
70 #define TBCR1       (BaseAddr+SHIFT(6))
71 #define ISR         (BaseAddr+SHIFT(7))    /* interrupt status register */
72
73 #define RSAR0       (BaseAddr+SHIFT(8))    /* dma read address */
74 #define RSAR1       (BaseAddr+SHIFT(9))
75 #define RBCR0       (BaseAddr+SHIFT(10))   /* dma read byte count */
76 #define RBCR1       (BaseAddr+SHIFT(11))
77
78 #define RCR         (BaseAddr+SHIFT(12))   /* receive config */
79 #define TCR         (BaseAddr+SHIFT(13))   /* transmit config */
80 #define DCR         (BaseAddr+SHIFT(14))   /* data config */
81 #define IMR         (BaseAddr+SHIFT(15))   /* interrupt mask */
82
83 #define ID8019L     (BaseAddr+SHIFT(10))
84 #define ID8019H     (BaseAddr+SHIFT(11))
85
86 /* page 1 */
87 #define PAR0        (BaseAddr+SHIFT(1))
88 #define PAR1        (BaseAddr+SHIFT(2))
89 #define PAR2        (BaseAddr+SHIFT(3))
90 #define PAR3        (BaseAddr+SHIFT(4))
91 #define PAR4        (BaseAddr+SHIFT(5))
92 #define PAR6        (BaseAddr+SHIFT(6))
93
94 #define CURR        (BaseAddr+SHIFT(7))
95 #define MAR0        (BaseAddr+SHIFT(8))
96 #define MAR1        (BaseAddr+SHIFT(9))
97 #define MAR2        (BaseAddr+SHIFT(10))
98 #define MAR3        (BaseAddr+SHIFT(11))
99 #define MAR4        (BaseAddr+SHIFT(12))
100 #define MAR5        (BaseAddr+SHIFT(13))
```

```
101 #define      MAR6  (BaseAddr+SHIFT(14))  
102 #define      MAR7  (BaseAddr+SHIFT(15))  
103  
104 /* page 2 */  
105  
106 /* page 3 */  
107 #define      CR9346    (BaseAddr+SHIFT(1))  
108 #define      CONFIG0   (BaseAddr+SHIFT(3))  
109 #define      CONFIG1   (BaseAddr+SHIFT(4))  
110 #define      CONFIG2   (BaseAddr+SHIFT(5))  
111 #define      CONFIG3   (BaseAddr+SHIFT(6))  
112
```

```
113 /*****
114     rtl8019.c
115     This software may be used and distributed according to the terms
116     of the GNU General Public License, incorporated herein by reference.
117 *****/
118
119
120 #include "rtl8019.h"
121
122 #define RTL8019_OP_16    1
123
124 #undef DEBUG
125 #define DEBUG    1
126 #ifdef DEBUG
127 #define TRACE(str, args...) printk(str, ## args)
128 #else
129 #define TRACE(str, args...)
130 #endif
131
132 #define outportb(port, data) *((volatile u8 *)(port)) = (u8)(data)
133 #define inportb(port)        *((volatile u8 *)(port))
134
135 #define outportw(port, data) *((volatile u16 *)(port)) = (u16)(data)
136 #define inportw(port)        *((volatile u16 *)(port))
137
138 #define ETH_FRAME_LEN        1514
139
140 #define RPSTART            0x4c
141 #define RPSTOP             0x80
142 #define SPSTART            0x40
143
144 static int timeout = 100; // tx watchdog ticks 100 = 1s
145 static char *version = "Rtl8019as driver for Philips LPC22xx: version 0.1\n";
146
147 /*
148  * This structure is private to each device. It is used to pass
149  * packets in and out, so there is place for a packet
150  */
151 struct nic_8019_priv {
152     struct net_device_stats stats;
153     spinlock_t lock;
154     struct sk_buff *skb;
155 };
156
157 *****/
158 static u8 rBNRY;
159 static u8 SrcMacID[ETH_ALEN] = {0x12,0x34,0x56,0x78,0x90,0xAB,};
160
161 static void SetRegPage( u8 PageIdx)
162 {
163     u8 temp;
```

```
164
165     temp = inportb(BaseAddr);
166     temp = (temp&0x3b)|(PageIndex<<6);
167     outportb(BaseAddr, temp);
168 }
169
170 irqreturn_t nic_8019_rx(int irq, void *dev_id, struct pt_regs *regs)
171 {
172     u8 RxPageBeg, RxPageEnd;
173     u8 RxNextPage;
174     u8 RxStatus;
175     u16 *data,temp;
176     u16 i, RxLength,RxLen;
177
178     struct sk_buff *skb;
179     struct net_device *dev = (struct net_device *) dev_id;
180     struct nic_8019_priv *priv = (struct nic_8019_priv *) dev->priv;
181
182     TRACE("TX/RX Interrupt!\n");
183     spin_lock(&priv->lock);
184     SetRegPage(0);
185     outportb(BNRY, rBNRY);
186     RxStatus = inportb(ISR);
187     printk("RxStatus=0x%x\n", RxStatus);
188     if (RxStatus & 2) {
189         outportb(ISR, 0x2);           //clr TX interrupt
190         priv->stats.tx_packets++;
191         TRACE("transmit one packet complete!\n");
192     }
193
194     if (RxStatus & 1) {
195         TRACE("Receive x packet....\n");
196         outportb(ISR, 0x1);           //clr Rx interrupt
197         SetRegPage(1);
198         RxPageEnd = inportb(CURR);
199
200         SetRegPage(0);
201         RxPageBeg = rBNRY+1;
202         if(RxPageBeg>=RPSTOP)
203             RxPageBeg = RPSTART;
204         outportb(BaseAddr, 0x22); // stop remote dma
205
206         //outport(RSAR0, RxPageBeg<<8);
207         //outport(RBCR0, 256);
208         outportb(RSAR0, 0);
209         outportb(RSAR1, RxPageBeg);
210         outportb(RBCR0, 4);
211         outportb(RBCR1, 0);
212         outportb(BaseAddr, 0xa);
213
214 #ifdef RTL8019_OP_16
```

```
215         temp      = importw(RWPORt);
216         RxNextPage = temp>>8;
217         RxStatus   = temp&0xff;
218         RxLength   = importw(RWPORt);
219     #else
220         RxStatus   = importb(RWPORt);
221         RxNextPage = importb(RWPORt);
222         RxLength   = importb(RWPORt);
223         RxLength |= importb(RWPORt)<<8;
224     #endif
225         TRACE("\nRxBegin = %x, RxEnd = %x, nextpage = %x, size = %i\n",
226             RxPageBeg, RxPageEnd, RxNextPage, RxLength);
227         RxLength -= 4;
228         if (RxLength>ETH_FRAME_LEN) {
229             if (RxPageEnd==RPSTART)
230                 rBNRY = RPSTOP-1;
231             else
232                 rBNRY = RxPageEnd-1;
233
234             outportb(BNRY, rBNRY);
235             TRACE("RxLength more long than %x\n", ETH_FRAME_LEN);
236             return IRQ_HANDLED;
237         }
238         skb = dev_alloc_skb(RxLength+2);
239         if (!skb) {
240             TRACE("Rtl8019as eth: low on mem - packet dropped\n");
241             priv->stats.rx_dropped++;
242             return IRQ_HANDLED;
243         }
244
245         skb->dev = dev;
246         skb_reserve(skb, 2);
247         skb_put(skb, RxLength);
248         data = ( u16 *)skb->data;
249
250         //      eth_copy_and_sum(skb, data, len, 0);
251         outportb(RSAR0, 4);
252         outportb(RSAR1, RxPageBeg);
253         outportb(RBCR0, RxLength);
254         outportb(RBCR1, RxLength>>8);
255         outportb(BaseAddr, 0xa);
256     #ifdef RTL8019_OP_16
257         i = 2;
258         data -= 2;
259         RxLen=(RxLength+1)/2;
260     #else
261         i = 4;
262         data -= 4;
263         RxLen=RxLength;
264     #endif
```

```
265         for(; RxLen--;) {
266 #ifdef RTL8019_OP_16
267             static const int cmp_val = 0x7f;
268 #else
269             static const int cmp_val = 0xff;
270 #endif
271             if (!(i & cmp_val)) {
272                 outportb(BNRY, RxPageBeg);
273                 RxPageBeg++;
274                 if(RxPageBeg>=RPSTOP)
275                     RxPageBeg = RPSTART;
276             }
277 #ifdef RTL8019_OP_16
278             data[i++] = inportw(RWPORT);
279             TRACE("%2X,%2X,", data[i-1]&0xff,data[i-1]>>8);
280 #else
281             data[i++] = inportb(RWPORT);
282             TRACE("%2X,", data[i-1]);
283 #endif
284         }
285
286         TRACE("\n");
287         outportb(BNRY, RxPageBeg);
288         rBNRY = RxPageBeg;
289
290         skb->protocol = eth_type_trans(skb, dev);
291         TRACE("\nprotocol=%x\n", skb->protocol);
292         priv->stats.rx_packets++;
293         priv->stats.rx_bytes +=RxLength;
294         netif_rx(skb);
295     } else {
296         outportb(ISR, 0xfe);
297     }
298
299     spin_unlock(&priv->lock);
300     return IRQ_HANDLED;
301 }
302
303
304 /*
305  * Open and Close
306  */
307 static int nic_8019_open(struct net_device *dev)
308 {
309     int i,j;
310
311     MOD_INC_USE_COUNT;
312     TRACE("open\n");
313     // Disable irqs
314     disable_irq(dev->irq);
315     // register rx isr
```

```
316     if (request_irq(dev->irq, &nic_8019_rx, SA_INTERRUPT, "eth rx isr", dev)) {  
317         printk(KERN_ERR "Rtl8019: Can't get irq %d\n", dev->irq);  
318         return -EAGAIN;  
319     }  
320  
321     // wake up Rtl8019as  
322     SetRegPage(3);  
323     outportb(CR9346, 0xcf);           //set eem1-0, 11 ,enable write config  
register  
324     outportb(CONFIG3, 0x60);        //clear pwrdsn, sleep mode, set led0 as led_col,  
led1 as led_crs  
325     outportb(CR9346, 0x3f);        //disable write config register  
326  
327     // initialize  
328     outportb(RstAddr, 0x5a);  
329     i = 20000;  
330     while(i--);  
331  
332     SetRegPage(0);  
333     inportb(ISR);  
334     outportb(BaseAddr, 0x21); /* set page 0 and stop */  
335     outportb(Pstart, RPSTART); /* set Pstart 0x4c */  
336     outportb(Pstop, RPSTOP); /* set Pstop 0x80 */  
337     outportb(TPSR, SPSTART); /* SPSTART page start register, 0x40 */  
338     outportb(BNRY, RPSTART); /* BNRY-> the last page has been read */  
339     outportb(TCR, 0xe0);      /* set TCR 0xe0 */  
340     outportb(DCR, 0xc9);      /* set DCR 0xc9, 16bit DMA */  
341  
342     outportb(IMR, 0x03);      /* set IMR 0x03, enable tx rx int */  
343     outportb(ISR, 0xff);      /* clear ISR */  
344  
345     SetRegPage(1);  
346     for(i=0; i<6; i++)  
347         outportb(BaseAddr+(1+i)*2, dev->dev_addr[i]); // set mac id  
348  
349     outportb(CURR, RPSTART+1);  
350     outportb(MAR0, 0x00);  
351     outportb(MAR1, 0x41);  
352     outportb(MAR2, 0x00);  
353     outportb(MAR3, 0x80);  
354     outportb(MAR4, 0x00);  
355     outportb(MAR5, 0x00);  
356     outportb(MAR6, 0x00);  
357     outportb(MAR7, 0x00);  
358     outportb(BaseAddr, 0x22); /* set page 0 and start */  
359     rBNRY = RPSTART;  
360     enable_irq(dev->irq);  
361     // Start the transmit queue  
362     netif_start_queue(dev);  
363  
364     return 0;
```

```
365  }
366
367 static int nic_8019_stop(struct net_device *dev)
368 {
369     TRACE("stop\n");
370     SetRegPage(3);
371     outportb(CR9346, 0xcf);           // set eem1-0, 11 ,enable write config
register
372     outportb(CONFIG3, 0x66);        // enter pwrdown, sleep mode, set led0 as led_col,
led1 as led_crs
373     outportb(CR9346, 0x3f);        // disable write config register
374
375     free_irq(dev->irq, dev);
376     netif_stop_queue(dev);
377     MOD_DEC_USE_COUNT;
378
379     return 0;
380 }
381
382 static int nic_8019_start_xmit(struct sk_buff *skb, struct net_device *dev)
383 {
384     int i;
385     u16 len,TxLen;
386     u16 *data;
387     struct nic_8019_priv *priv = (struct nic_8019_priv *) dev->priv;
388
389     TRACE("start_xmit\n");
390
391     len = skb->len < ETH_ZLEN ? ETH_ZLEN : skb->len;
392     TRACE("\nTx Length = %i,%x,%x\n", len, skb->data[12], skb->data[13]);
393     data =(u16*) skb->data;
394
395     outportb(BaseAddr,0x22);    //switch to page 0 and stop remote dma
396     if (inportb(BaseAddr)&4)    // last remote dma not complete,return 1 echo
busy(error),retransmit next
397     return 1;
398 #ifdef bug_fix_for_write
399     //read page 42,0,42,0 before write if you have problem
400 #endif
401     outportb(RSAR0, 0);
402     outportb(RSAR1, SPSTART);
403     outportb(RBCR0, len&0xff);
404     outportb(RBCR1, len>>8);
405     outportb(BaseAddr, 0x12);   //begin remote write
406     dev->trans_start = jiffies;
407 #ifdef RTL8019_OP_16
408     TxLen=(len+1)/2;
409 #else
410     TxLen=len;
411 #endif
412     for(i=0; i<TxLen; i++) {
```

```
413 #ifdef RTL8019_OP_16
414         outportw(RWPORT, data[i]);          // copy data to nic ram
415         TRACE("%2X,%2X,",data[i]&0xff,data[i]>>8);
416 #else
417         outportb(RWPORT, data[i]);          // copy data to nic ram
418         TRACE("%2X,",skb->data[i]);
419 #endif
420     }
421
422     TRACE("\n");
423     outportb(TPSR, SPSTART);           // transmit begin page 0x40
424     outportb(TBCR0, len&0xff);
425     outportb(TBCR1, len>>8);
426     outportb(BaseAddr, 0x1e);        // begin to send packet
427     dev_kfree_skb(skb);
428     return 0;
429 }
430
431 static struct net_device_stats *nic_8019_get_stats(struct net_device *dev)
432 {
433     struct nic_8019_priv *priv = (struct nic_8019_priv *) dev->priv;
434     TRACE("get_stats\n");
435     return &priv->stats;
436 }
437
438 /*****static int nic_8019_init(struct net_device *dev)
439 {
440     int i;
441     TRACE("init\n");
442     ether_setup(dev);      // Assign some of the fields
443
444     // set net_device methods
445     dev->open = nic_8019_open;
446     dev->stop = nic_8019_stop;
447     dev->get_stats = nic_8019_get_stats;
448     dev->hard_start_xmit = nic_8019_start_xmit;
449
450     // set net_device data members
451     dev->watchdog_timeo = timeout;
452     dev->irq = 14; //LPC22xx: EXT0
453     dev->dma = 0;
454
455     // set MAC address manually
456     printk(KERN_INFO "%s: ", dev->name);
457     for(i=0; i<6; i++) {
458         dev->dev_addr[i] = SrcMacID[i];
459         printk("%2.2x%c", dev->dev_addr[i], (i==5) ? ' ' : ':');
460     }
461     printk("\n");
462
463 }
```

```
464     SET_MODULE_OWNER(dev);  
465  
466     dev->priv = kmalloc(sizeof(struct nic_8019_priv), GFP_KERNEL);  
467     if(dev->priv == NULL)  
468         return -ENOMEM;  
469  
470     memset(dev->priv, 0, sizeof(struct nic_8019_priv));  
471     spin_lock_init(&((struct nic_8019_priv *) dev->priv)->lock);  
472     return 0;  
473 }  
474  
475 static struct net_device nic_8019_netdevs = {  
476     init: nic_8019_init,  
477 };  
478  
479 /*  
480 * Finally, the module stuff  
481 */  
482 int __init nic_8019_init_module(void)  
483 {  
484     int result;  
485     TRACE("init_module\n");  
486  
487     //Print version information  
488     printk(KERN_INFO "%s", version);  
489  
490     //register_netdev will call nic_8019_init()  
491     if((result = register_netdev(&nic_8019_netdevs)))  
492         printk("Rtl8019as eth: Error %i registering device \'%s\'\n", result,  
        nic_8019_netdevs.name);  
493  
494     return result ? 0 : -ENODEV;  
495 }  
496  
497 void __exit nic_8019_cleanup(void)  
498 {  
499     TRACE("cleanup\n");  
500     kfree(nic_8019_netdevs.priv);  
501     unregister_netdev(&nic_8019_netdevs);  
502     return;  
503 }  
504  
505 module_init(nic_8019_init_module);  
506 module_exit(nic_8019_cleanup);  
507 MODULE_DESCRIPTION("Rtl8019as ethernet driver");
```

5. Legal information

5.1 Definitions

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For sales office addresses, email to: salesaddresses@nxp.com

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